Motivation

- Different components require different (stable) supply voltages
- Several DC-DC converters are typically necessary to convert the battery voltage into the different required levels
- Power conversion should be as efficient as possible
  - Resource savings
  - Extend lifetime of battery-powered devices

Control theory

- Needed to tightly regulate the output voltage of a DC-DC converter
- Can play a key role in the efficiency
  - Reduce the switching activity (e.g. DCM, PFM)
  - Reduce under- and overshoots during transient ⇒ reference value can be reduced
- Alternative and modern structures alternative to linear PID worth exploring, e.g. Sliding Mode:
  - Improved dynamic performance (e.g. load transient)
  - Improved efficiency
  - Robustness to parameter variations

Implementation

- Choice between analog and digital should be made with care
- Digital implementation gives more flexibility
  - Power consumption of the additional ADC must be evaluated
  - Particularly critical at high switching frequencies
- Analog implementation generally offers faster dynamic response and lower power consumption

Challenges

- Maximize efficiency
- Optimize the control structures
  - Use innovative control techniques (especially with digital implementations)
    - Sliding mode
    - $H_{\infty}$ control
    - Fuzzy logic
    - Predictive control
  - Auto-tuning of the control coefficients
- Fully integrated DC-DC converters
- Output filter integrated on-chip
- Requires extremely high switching frequencies
- Energy harvesting

Application example – Buck-Boost converter for mobile devices

- Capable of stepping up and down the input (battery) voltage
- Analog implementation for high-performance and low-power
- 0.13 µm CMOS technology
- Efficiency improvement via control algorithm (efficient operating mode selection)

Bibliography